

# Two-Way Automata Making Choices Only at the Endmarkers

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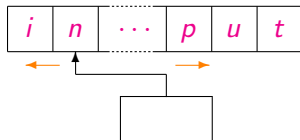
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# Finite State Automata



Base versions:

- ▶ one-way deterministic (1DFA)
- ▶ one-way nondeterministic (1NFA)

Possible variants:

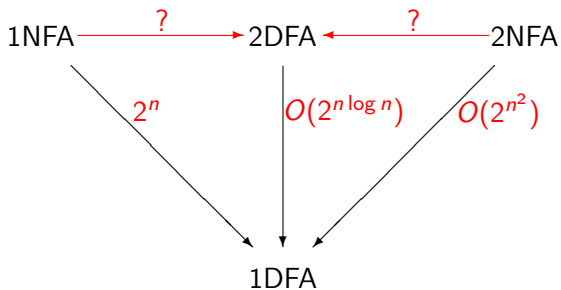
- ▶ *two-way automata*: input head moving forth and back
  - 2DFA
  - 2NFA
- ▶ alternating automata
- ▶ ...

What about the power of these models?

They share the same computational power, namely they characterize the class of *regular languages*, however...

...some of them are more succinct

# Costs of the Optimal Simulations Between Automata

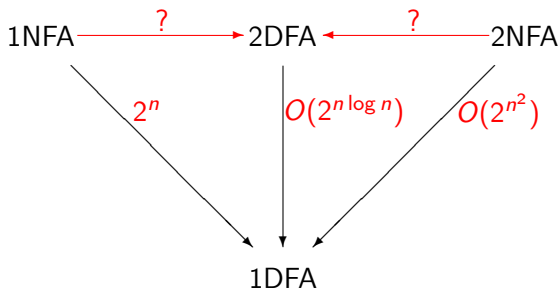


[Rabin&Scott '59, Shepardson '59, Meyer&Fischer '71, ...]

## Question

*How much the possibility of moving the input head forth and back is useful to eliminate the nondeterminism?*

# Costs of the Optimal Simulations Between Automata



## Problem ([Sakoda&Sipser '78])

*Do there exist polynomial simulations of*

- ▶ *1NFAs by 2DFAs*
- ▶ *2NFAs by 2DFAs ?*

## Conjecture

*These simulations are not polynomial*

# Sakoda&Sipser Question: Upper and Lower Bounds

- ▶ **Exponential upper bounds**

deriving from the simulations by 1DFAs

- ▶ **Polynomial lower bounds**

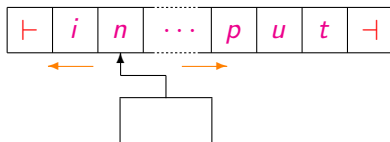
for the cost  $c(n)$  of simulation of 1NFAs by 2DFAs:

- $c(n) \in \Omega\left(\frac{n^2}{\log n}\right)$  [Berman&Lingas '77]
- $c(n) \in \Omega(n^2)$  [Chrobak '86]

# Sakoda and Sipser Question

- ▶ Very difficult in its general form
- ▶ Not very encouraging obtained results:
  - Lower and upper bounds too far  
(Polynomial vs exponential)
- ▶ Hence:
  - Try to attack restricted versions of the problem!

## Two-Way Automata: Few Technical Details



- ▶ Input surrounded by the endmarkers  $\vdash$  and  $\dashv$
- ▶  $w \in \Sigma^*$  is accepted iff there is a computation
  - with input tape  $\vdash w \dashv$
  - starting at the left endmarker  $\vdash$  in the initial state
  - reaching a final state (on the left endmarker)



## 2NFAs vs 2DFAs: Restricted Versions

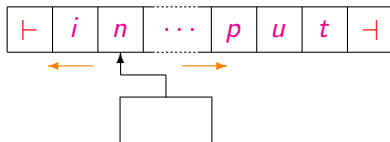
Previous works:

- (i) Restrictions on the *simulating* machines (i.e., resulting 2DFAs)
  - ▶ sweeping automata [Sipser '80]
  - ▶ oblivious automata [Hromkovič&Schnitger '03]
  - ▶ “few reversal” automata [Kapoutsis '11]
  
- (ii) Restrictions on the *languages*
  - ▶ unary regular languages [Geffert Mereghetti&Pighizzini '03]

In this work we use a different approach:

- (iii) Restrictions on the *simulated* machines (i.e., given 2NFAs)

# Outer Nondeterministic Automata (ONFAs)



In the paper, we consider the following model:

## Definition

A two-way automaton is said to be *outer nondeterministic* iff nondeterministic choices are allowed *only* when the input head is scanning the endmarkers

# Unary 2NFAs vs ONFAs

## Normal Form for Unary 2NFAs [Geffert Mereghetti&Pighizzini '03]

- ▶ *Nondeterministic choices* only at the endmarkers
- ▶ *Head reversals* only at the endmarkers
- ▶ In each sweep the input length modulo one integer is counted

## Outer Nondeterministic Automata

- ▶ No restrictions on the *input alphabet*
- ▶ No restrictions on *head reversals*
- ▶ *Deterministic transitions* on “real” input symbols
- ▶ *Nondeterministic choices* only at the endmarkers

## Unary 2NFAs are a very restricted version of 2ONFAs!

- ▶ We extended to 2ONFAs previous results on unary 2NFAs

# Outer nondeterministic automata (ONFAs): tools

## Main tool: procedure *reach(p, q)*

- ▶ Checks the existence of a computation segment
  - from the left endmarker in the state  $p$
  - to the left endmarker in the state  $q$
  - not visiting the left endmarker in between

## *Accepting computation:*

sequence of states  $q_0, q_1, \dots, q_f$  visited at the left endmarker:

- ▶  $q_0$  initial state
- ▶ for  $i = 1, \dots, f$   $reach(q_{i-1}, q_i) = true$
- ▶  $q_f$  final state

## Outer nondeterministic automata (ONFAs): tools

- ▶ How to deal with loops?
- ▶ Two kinds of loops:
  - loops visiting the endmarkers
  - loops inside the “real” input

## Loops visiting the endmarkers

- ▶ Loops involving endmarkers can contain nondeterministic choices
- ▶ If a computation visits the left endmarker twice in the same state  $q$  then there is a shorter “equivalent” computation
- ▶ We can consider only computations visiting the left endmarker  $\leq \#Q$  times

# Loops inside the “real” input

Procedure  $reach(p, q)$ :

- ▶ “Backward search” from  $q$  to  $p$
- ▶ In this way loops are avoided
- ▶ Finite control with a *linear number of states*

The technique:

- ▶ Introduced by Sipser for the complementation of space bounded Turing machines [Sipser '80]
- ▶ Modified for the complementation of 2DFAs [Geffert Mereghetti&Pighizzini '07]
- ▶ Extended in our paper to 2ONFAs

# Results

- (i) Subexponential simulation of 2ONFAs by 2DFAs  
Verify that  $q_f$  is reachable from  $q_0$   
by visiting the left endmarker  $\leq \#Q$  times  
(divide-and-conquer algorithm)
  
- (ii) Polynomial complementation of 2ONFAs  
Inductive counting argument
  
- (iii) Polynomial simulation of 2ONFAs by 2DFAs  
*under the condition*  $L = NL$   
Reduction to graph accessibility problem
  
- (iv) Polynomial simulation of 2ONFAs by unambiguous 2ONFAs  
Reduction to graph accessibility problem  
combined with  $NL/poly \subseteq UL$  [Reinhardt&Allender '00]



## Results: Alternating Case (2ONFAs)

At the endmarkers, universal and existential states are allowed

- (v) Polynomial simulation of 2OAFAs by 2DFAs under  $L = P$
- (vi) Polynomial simulation of 2OAFAs by 2NFAs under  $NL = P$

For both:

Reduction to the Alternating Graph Accessibility Problem

## Final Remarks

- ▶ We extended several results from the unary to the general case for 2NFAs
- ▶ In the unary case, restricting the nondeterminism to the endmarkers does not significantly change the size of 2NFAs (normal form)
- ▶ In the general case, is there some “simple way” to restrict the nondeterminism?
- ▶ Does it is possible to extend our results to some wider class of 2NFAs?
- ▶ Interesting connections with complexity theory:
  - Results connected with classical complexity questions
  - Proof techniques derived from space complexity